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Dynamic output feedback control for nonlinear large-scale ...

A feedback control system is formed of a unit-gain integral controller, a mechanical filter microsystem (plant), which is formed of two shuttle masses, and a connecting micro spring, with one mass being subjected to viscous damping and connected to another micro spring to the substrate.

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ter 6, we formally introduce feedback systems by demonstrating how state space control laws can be designed. This is followed in Chapter 7 by material on output feedback and estimators. Chapters 6 and 7 introduce the key concepts of reachability and observability, which give tremendous insight into the choice of actuators

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order differential equation in $y(t)$.
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The definition of a closed loop control system according to the British Standard Institution is "a control system possessing monitoring feedback, the deviation signal formed as a result of this feedback being used to control the action of a final control element in such a way as to tend to reduce the deviation to zero."

Control theory - Wikipedia

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Feedback Control of Dynamic Systems, Third Edition, retains its balanced coverage of modern and classical topics, the early incorporation of design aspects, and its discussion of analysis techniques; all hallmark features that established it as the authoritative controls text.

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